

Note: Div, Grad, Curl all are first derivatives.

Laplacian :-

Laplacian is defined for both scalar & vector

$$\vec{\nabla} \cdot \vec{\nabla} = \nabla^2$$

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$A_x, A_y, A_z \rightarrow \text{Scalar}$

Cartesian :-

$$\nabla^2 T = \left(\frac{\partial^2}{\partial x^2} T + \frac{\partial^2}{\partial y^2} T + \frac{\partial^2}{\partial z^2} T \right) \quad T \rightarrow \text{Scalar}$$

for a vector,

$$\begin{aligned} \nabla^2 \vec{A} = & \left(\frac{\partial^2}{\partial x^2} A_x + \frac{\partial^2}{\partial y^2} A_x + \frac{\partial^2}{\partial z^2} A_x \right) \hat{i} + \left(\frac{\partial^2}{\partial x^2} A_y + \frac{\partial^2}{\partial y^2} A_y + \frac{\partial^2}{\partial z^2} A_y \right) \hat{j} \\ & + \left(\frac{\partial^2}{\partial x^2} A_z + \frac{\partial^2}{\partial y^2} A_z + \frac{\partial^2}{\partial z^2} A_z \right) \hat{k} \end{aligned}$$

$$\boxed{\nabla^2 V = 0}$$

Laplacian eqⁿ

$$\boxed{\nabla^2 V = -\rho/\epsilon_0}$$

Poisson eqⁿ

Spherical Polar

$$\begin{aligned} \nabla^2 T = & \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial T}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T}{\partial \theta} \right) + \\ & \frac{1}{r^2 \sin^2 \theta} \left(\frac{\partial^2 T}{\partial \phi^2} \right) \end{aligned}$$

Cylindrical

$$\nabla^2 T = \frac{1}{s} \frac{\partial}{\partial s} \left(s \frac{\partial T}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2 T}{\partial \phi^2} + \frac{\partial^2 T}{\partial z^2}$$

Table for General Formula

System	u	v	w	f	g	h
C	x	y	z	1	1	1
S.P.	r	θ	ϕ	1	r	$r \sin \theta$
Cy.	s	ϕ	z	1	s	1

(i) Gradient:-

$$\vec{\nabla} T = \frac{1}{f} \frac{\partial T}{\partial u} \hat{u} + \frac{1}{g} \frac{\partial T}{\partial v} \hat{v} + \frac{1}{h} \frac{\partial T}{\partial w} \hat{w}$$

(ii) Divergence:-

$$\vec{\nabla} \cdot \vec{A} = \frac{1}{fgh} \left[\frac{\partial}{\partial u} (gh A_u) + \frac{\partial}{\partial v} (fh A_v) + \frac{\partial}{\partial w} (fg A_w) \right]$$

(iii) Curl:-

$$\vec{\nabla} \times \vec{A} = \frac{1}{fgh} \begin{vmatrix} f\hat{u} & g\hat{v} & h\hat{w} \\ \frac{\partial}{\partial u} & \frac{\partial}{\partial v} & \frac{\partial}{\partial w} \\ fA_u & gA_v & hA_w \end{vmatrix}$$

(iv) Laplacian:-

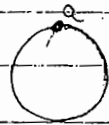
$$\nabla^2 T = \frac{1}{fgh} \left[\frac{\partial}{\partial u} \left(\frac{gh}{f} \frac{\partial T}{\partial u} \right) + \frac{\partial}{\partial v} \left(\frac{fh}{g} \frac{\partial T}{\partial v} \right) + \frac{\partial}{\partial w} \left(\frac{fg}{h} \frac{\partial T}{\partial w} \right) \right]$$

Theorems

1) Gradient Theorem

$$\int_a^b (\nabla T) \cdot d\vec{r} = \int_a^b dT = T(b) - T(a)$$

$$\oint (\nabla T) \cdot d\vec{r} = 0$$



bcz in close line integral initial & final points are same.

2) Divergence Theorem / Gauss Theorem is used to convert closed surface integral into volume integral.

$$\oint_S \vec{A} \cdot d\vec{s} = \int_V (\nabla \cdot \vec{A}) dV$$

* Close surfaces are those surfaces which bounds some volume. It can be used for sphere, cylinder, cube but not for a disc bcz it is not a closed surface.

3) Curl Theorem / Stoke's Theorem is used to convert closed line integral into ^{open} surface integral.

$$\oint_C \vec{A} \cdot d\vec{l} = \int_S (\nabla \times \vec{A}) \cdot d\vec{s}$$

* closed line curve are those which bounding some surface,



≡

————— x Not a closed line curve.